

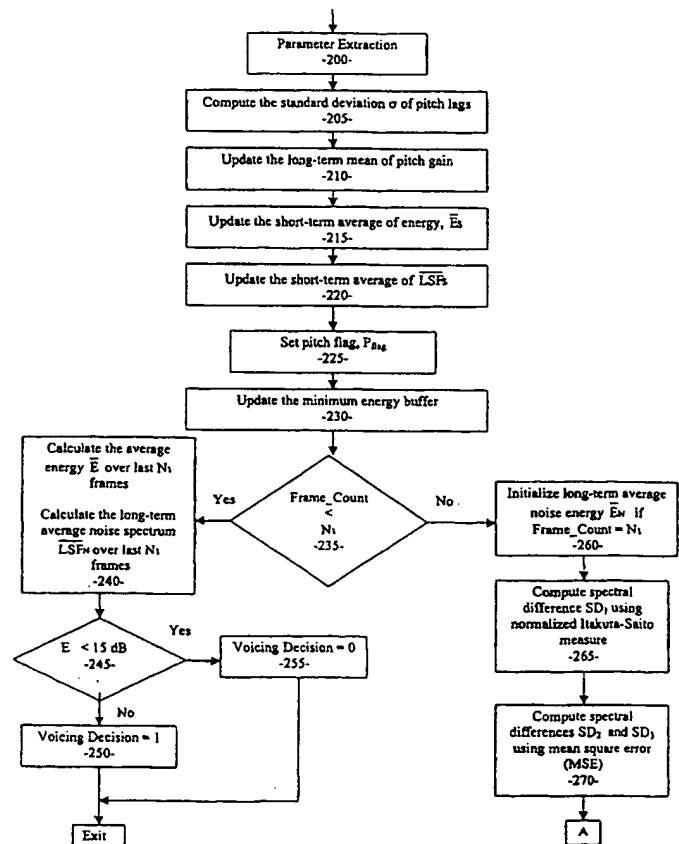
INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(51) International Patent Classification ⁷ : G10L 11/02	A1	(11) International Publication Number: WO 00/17856 (43) International Publication Date: 30 March 2000 (30.03.00)
(21) International Application Number: PCT/US99/19806 (22) International Filing Date: 27 August 1999 (27.08.99) (30) Priority Data: 09/156,416 18 September 1998 (18.09.98) US (71) Applicant: CONEXANT SYSTEMS, INC. [US/US]; Joseph King, 4311 Jamboree Road, Newport Beach, CA 92660-3095 (US). (72) Inventors: BENYASSINE, Adil; 1305 Reggio Aisle, Irvine, CA 92614 (US). SHLOMOT, Eyal; 86 Costero Aisle, Irvine, CA 92614 (US). (74) Agent: GESS, Albin, H.; Price, Gess & Ubell, 2100 S.E. Main Street, Suite 250, Irvine, CA 92614 (US).		(81) Designated States: CA, CN, JP, European patent (AT, BE, CH, CY, DE, DK, ES, FI, FR, GB, GR, IE, IT, LU, MC, NL, PT, SE). Published <i>With international search report.</i>

(54) Title: METHOD AND APPARATUS FOR DETECTING VOICE ACTIVITY IN A SPEECH SIGNAL

(57) Abstract

A method and apparatus for generating frame voicing decisions for an incoming speech signal having periods of active voice and non-active voice for a speech encoder in a speech communications system. A predetermined set of parameters is extracted from the incoming speech signal, including a pitch gain and a pitch lag. A frame voicing decision is made for each frame of the incoming speech signal according to values calculated from the extracted parameters. The predetermined set of parameters further includes a frame full band energy, and a set of spectral parameters called Line Spectral Frequencies (LSF).



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METHOD AND APPARATUS FOR DETECTING VOICE ACTIVITY IN A SPEECH SIGNAL

5

BACKGROUND OF THE INVENTION

1. Field of the Invention

The present invention relates generally to the field of speech coding in communication systems, and more particularly to detecting voice activity in a communications system.

10

2. Description of Related Art

Modern communication systems rely heavily on digital speech processing in general, and digital speech compression in particular, in order to provide efficient systems. Examples of such communication systems are digital telephony trunks, voice mail, voice annotation, answering machines, digital voice over data links, etc.

15

A speech communication system is typically comprised of an encoder, a communication channel and a decoder. At one end of a communications link, the speech encoder converts a speech signal which has been digitized into a bit-stream. The bit-stream is transmitted over the communication channel (which can be a storage medium), and is converted again into a digitized speech signal by the decoder at the other end of the communications link.

20

The ratio between the number of bits needed for the representation of the digitized speech signal and the number of bits in the bit-stream is the compression ratio. A compression ratio of 12 to 16 is presently achievable, while still maintaining a high quality reconstructed speech signal.

25

A significant portion of normal speech is comprised of silence, up to an average of 60% during a two-way conversation. During silence, the speech input

device, such as a microphone, picks up the environment or background noise. The noise level and characteristics can vary considerably, from a quiet room to a noisy street or a fast moving car. However, most of the noise sources carry less information than the speech signal and hence a higher compression ratio is achievable during the silence periods. In the following description, speech will be denoted as "active-voice" and silence or background noise will be denoted as "non-active-voice".

The above discussion leads to the concept of dual-mode speech coding schemes, which are usually also variable-rate coding schemes. The active-voice and the non-active voice signals are coded differently in order to improve the system efficiency, thus providing two different modes of speech coding. The different modes of the input signal (active-voice or non-active-voice) are determined by a signal classifier, which can operate external to, or within, the speech encoder. The coding scheme employed for the non-active-voice signal uses less bits and results in an overall higher average compression ratio than the coding scheme employed for the active-voice signal. The classifier output is binary, and is commonly called a "voicing decision." The classifier is also commonly referred to as a Voice Activity Detector ("VAD").

A schematic representation of a speech communication system which employs a VAD for a higher compression rate is depicted in Figure 1. The input to the speech encoder 110 is the digitized incoming speech signal 105. For each frame of a digitized incoming speech signal the VAD 125 provides the voicing decision 140, which is used as a switch 145 between the active-voice encoder 120 and the non-active-voice encoder 115. Either the active-voice bit-stream 135 or the non-active-voice bit-stream 130, together with the voicing decision 140 are transmitted through the communication channel 150. At the speech decoder 155 the voicing decision is used in the switch 160 to select the non-active-voice decoder 165 or the active-voice decoder 170. For each frame, the output of either decoders is used as the reconstructed speech 175.

An example of a method and apparatus which employs such a dual-mode system is disclosed in U.S. Patent No. 5,774,849, commonly assigned to the present

assignee and herein incorporated by reference. According to U.S. Patent No. 5,774,849, four parameters are disclosed which may be used to make the voicing decision. Specifically, the full band energy, the frame low-band energy, a set of parameters called Line Spectral Frequencies ("LSF") and the frame zero crossing rate are compared to a long-term average of the noise signal. While this algorithm provides satisfactory results for many applications, the present inventors have determined that a modified decision algorithm can provide improved performance over the prior art voicing decision algorithms.

SUMMARY OF THE INVENTION

10 A method and apparatus for generating frame voicing decisions for an incoming speech signal having periods of active voice and non-active voice for a speech encoder in a speech communications system. A predetermined set of parameters is extracted from the incoming speech signal, including a pitch gain and a pitch lag. A frame voicing decision is made for each frame of the incoming speech
15 signal according to values calculated from the extracted parameters. The predetermined set of parameters further includes a frame full band energy, and a set of spectral parameters called Line Spectral Frequencies (LSF).

BRIEF DESCRIPTION OF THE DRAWINGS

20 The exact nature of this invention, as well as its objects and advantages, will become readily apparent from consideration of the following specification as illustrated in the accompanying drawings, in which like reference numerals designate like parts throughout the figures thereof, and wherein:

Figure 1 is a block diagram representation of a speech communication
25 system using a VAD;

Figures 2(A) and 2(B) are process flowcharts illustrating the operation of the VAD in accordance with the present invention; and

Figure 3 is a block diagram illustrating one embodiment of a VAD according to the present invention.

DETAILED DESCRIPTION
OF THE PREFERRED EMBODIMENTS

The following description is provided to enable any person skilled in the art to make and use the invention and sets forth the best modes contemplated by the inventor for carrying out the invention. Various modifications, however, will remain readily apparent to those skilled in the art, since the basic principles of the present invention have been defined herein specifically to provide a voice activity detection method and apparatus.

In the following description, the present invention is described in terms of functional block diagrams and process flow charts, which are the ordinary means for those skilled in the art of speech coding for describing the operation of a VAD. The present invention is not limited to any specific programming languages, or any specific hardware or software implementation, since those skilled in the art can readily determine the most suitable way of implementing the teachings of the present invention.

In the preferred embodiment, a Voice Activity Detection (VAD) module is used to generate a voicing decision which switches between an active-voice encoder/decoder and a non-active-voice encoder/decoder. The binary voicing decision is either 1 (TRUE) for the active-voice or 0 (FALSE) for the non-active-voice.

The VAD process flowchart is illustrated in Figures 2(A) and 2(B). The VAD operates on frames of digitized speech. The frames are processed in time order and are consecutively numbered from the beginning of each conversation/recording. The illustrated process is performed once per frame.

At the first block 200, four parametric features are extracted from the input signal. Extraction of the parameters can be shared with the active-voice encoder module 120 and the non-active-voice encoder module 115 for computational efficiency. The parameters are the frame full band energy, a set of spectral parameters called Line Spectral Frequencies ("LSF"), the pitch gain and the pitch lag. A set of

linear prediction coefficients is derived from the auto correlation and a set of

$\{\overline{LSF}_i\}_{i=1}^p$ is derived from the set of linear prediction coefficients, as described in ITU-T, Study Group 15 Contribution - Q. 12/15, Draft Recommendation G.729, June 8, 1995, Version 5.0, or DIGITAL SPEECH - Coding for Low Bit Rate Communication Systems by A.M. Kondo, John Wiley & Son, 1994, England. The full band energy E is the logarithm of the normalized first auto correlation coefficient $R(0)$:

$$E = 10 \cdot \log_{10} \left[\frac{1}{N} R(0) \right],$$

where N is a predetermined normalization factor.

- 10 The pitch gain is a measure of the periodicity of the input signal. The higher the pitch gain, the more periodic the signal, and therefore the greater the likelihood that the signal is a speech signal. The pitch lag is the fundamental frequency of the speech (active-voice) signal.

After the parameters are extracted, the standard deviation σ of the pitch lags of the last four previous frames are computed at block 205. The long-term mean of the pitch gain is updated with the average of the pitch gain from the last four frames at block 210. In the preferred embodiment, the long-term mean of the pitch gain is calculated according to the following formula:

$$\overline{P_{\text{gain}}} = 0.8 * \overline{P_{\text{gain}}} + 0.2 * [\text{average of last four frames}]$$

20

The short-term average of energy, $\overline{E_s}$, is updated at block 215 by averaging the last three frames with the current frame energy. Similarly, the short-term average of LSF vectors, \overline{LSFs} , is updated at block 220 by averaging the last three LSF frame vectors with the current LSF frame vector extracted by the parameter extractor at block 200. If the standard deviation σ is less than T_1 or the long-term mean of the pitch gain is greater than T_2 , then a flag P_{flag} is set to one, otherwise P_{flag}

equals zero at block 225.

If $\sigma < T_1$ OR $P_{\text{gain}} > T_2$, then $P_{\text{flag}} = 1$, else $P_{\text{flag}} = 0$.

In the preferred embodiment, $T_1 = 1.2$ and $T_2 = 0.7$. At block 230, a minimum energy
 5 buffer is updated with the minimum energy value over the last 128 frames. In other words, if the present energy level is less than the minimum energy level determined over the last 128 frames, then the value of the buffer is updated, otherwise the buffer value is unchanged.

If the frame count (i.e. current frame number) is less than a
 10 predetermined frame count N_1 at block 235, where N_1 is 32 in the preferred embodiment, an initialization routine is performed by blocks 240 - 255. At block 240 the average energy \bar{E} , and the long-term average noise spectrum $\overline{LSF_N}$ are calculated over the last N_1 frames. The average energy \bar{E} is the average of the energy of the last N_1 frames. The initial value for \bar{E} , calculated at block 240, is:

15

$$\bar{E} = \frac{1}{N} \sum_{n=1}^N E$$

The long-term average noise spectrum $\overline{LSF_N}$ is the average of the LSF
 20 vectors of the last N_1 frames. At block 245, if the instantaneous energy E extracted at block 200 is less than 15 dB, then the voicing decision is set to zero (block 255), otherwise the voicing decision is set one (block 250). The processing for the frame is then completed and the next frame is processed, beginning with block 200.

The initialization processing of blocks 240-255 initializes the
 25 processing over the last few frames. It is not critical to the operation of the present invention and may be skipped. The calculations of block 240 are required, however.

for the proper operation of the invention and should be performed, even if the voicing decisions of blocks 245-255 are skipped. Also, during initialization, the voicing decision could always be set to "1" without significantly impacting the performance of the present invention.

5 If the frame count is not less than N_1 at block 235, then the first time through block 260 ($\text{Frame_Count} = N_1$), the long-term average noise energy \overline{E}_N is initialized by subtracting 12 dB from the average energy \overline{E} :

$$\overline{E}_N = \overline{E} - 12\text{dB}$$

10

Next, at block 265, a spectral difference value SD_1 is calculated using the normalized Itakura-Saito measure. The value SD_1 is a measure of the difference between two spectra (the current frame spectra represented by R and E_{π} , and the background noise spectrum represented by \vec{a}). The Itakura-Saito measure is a well-known algorithm in the speech processing art and is described in detail, for example, in *Discrete-Time Processing of Speech Signals*, Deller, John R., Proakis, John G. and Hansen, John H.L., 1987, pages 327-329, herein incorporated by reference. Specifically, SD_1 is defined by the following equation:

$$SD_1 = \frac{\vec{a}^T R \vec{a}}{E_{\pi}}$$

20

where E_{π} is the prediction error from linear prediction (LP) analysis of the current frame;

R is the auto-correlation matrix from the LP analysis of the current frame; and

25 \vec{a} is a linear prediction filter describing the background noise

obtained from \overline{LSFN} .

At block 270 the spectral differences SD_2 and SD_3 are calculated using a mean square error method according to the following equations:

$$5 \quad SD_2 = \sum_{i=1}^p [\overline{LSFs(i)} - \overline{LSFN(i)}]^2$$

$$SD_3 = \sum_{i=1}^p [\overline{LSFs(i)} - \overline{LSF(i)}]^2$$

Where \overline{LSFs} is the short-term average of LSF;

10 \overline{LSFN} is the long-term average noise spectrum; and

LSF is the current LSF extracted by the parameter extraction.

The long-term mean of SD_2 (sm_SD_2) in the preferred embodiment is
15 updated at block 275 according to the following equation:

$$sm_SD_2 = 0.4 * SD_2 + 0.6 * sm_SD_2$$

Thus, the long term mean of SD_2 is a linear combination of the past long-term mean
20 and the current SD_2 value.

The initial voicing decision, obtained in block 280, is denoted by I_{10} .

The value of I_{VD} is determined according to the following decision statements:

If $\bar{E}_s \geq \bar{E}_N + X_1 \text{ dB}$
 OR
 $E > \bar{E}_N + X_2 \text{ dB}$
 then IVD = 1;

 If $\bar{E}_s - \bar{E}_N < X_3 \text{ dB}$
 AND
 $sm_SD_2 < T_3$
 AND
 $Frame_Count > 128$
 then IVD = 0; else IVD = 1;

 If $E > 1/2 (E^{-1} + E^{-2}) + X_4 \text{ dB}$
 OR
 $SD_1 > 1.5$
 then Ivd = 1.

In the preferred embodiment, $X_1 = 1$, $X_2 = 3$, $X_3 = 2$, $X_4 = 7$, and $T_3 = 0.00012$.

- 5 The initial voicing decision is smoothed at block 285 to reflect the long term stationary nature of the speech signal. The smoothed voicing decision of the frame, the previous frame and the frame before the previous frame are denoted by S_{vd}^0 , S_{vd}^{-1} and S_{vd}^{-2} , respectively. Both S_{vd}^{-1} and S_{vd}^{-2} are initialized to 1 and $S_{vd}^0 = I_{vd}$. A Boolean parameter F_{vd}^{-1} is initialized to 1 and a counter denoted by C_e is initialized
- 10 to 0. The energy of the previous frame is denoted by E_{-1} . Thus, the smoothing stage is defined by:

```

if  $F_{VD}^{-1} = 1$  and  $I_{VD} = 0$  and  $S_{VD}^{-1} = 1$  and  $S_{VD}^{-2} = 1$ 
 $S_{VD}^0 = 1$ 
 $C_e = C_e + 1$ 
if  $C_e \leq T_4$  {
 $F_{VD}^{-1} = 1$ 
}
else {
 $F_{VD}^{-1} = 0$ 
 $C_e = 0$ 
}
}
else
 $F_{VD}^{-1} = 1$ 

```

C_e is reset to 0 if $S_{VD}^{-1} = 1$ and $S_{VD}^{-2} = 1$ and $I_{VD} = 1$.

If $P_{\text{flag}} = 1$, then $S_{VD}^0 = 1$

5

If $E < 15$ dB, then $S_{VD}^0 = 0$

10 In the preferred embodiment, $T_4 = 14$. The final value of S_{VD}^0 represents the final voicing decision, with a value of "1" representing an active voice speech signal, and a value of "0" representing a non-active voice speech signal.

F_{SD} is a flag which indicates whether consecutive frames exhibit spectral stationarity (i.e., spectrum does not change dramatically from frame to frame). F_{SD} is set at block 290, according to the following where C_s is a counter initialized to 0.

```

    If Frame_Count > 128 AND SD3 < Ts
    then
        Cs = Cs + 1
    else
        Cs = 0;
    If Cs > N
        FSD = 1
    else
        FSD = 0.

```

In the preferred embodiment, T₅ = 0.0005 and N = 20.

The running averages of the background noise characteristics are
 5 updated at the last stage of the VAD algorithm. At block 295 and 300, the following
 conditions are tested and the updating takes place only if these conditions are met:

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    If  $\overline{E}_s < \overline{E}_N + 3$  AND Pflag = 0
    then  $\overline{E}_N = \beta_{EN} * \overline{E}_N + (1 - \beta_{EN}) * [\max \text{ of } E \text{ AND } \overline{E}_s]$ 
    AND  $\overline{LSF}_N(i) = \beta_{LSF} * \overline{LSF}_N(i) + (1 - \beta_{LSF}) * LSF(i) \quad i = 1, \dots, p$ 
    If Frame_Count > 128 AND
         $\overline{E}_N < \text{Min}$  AND FSD = 1 AND Pflag = 0
    then  $\overline{E}_N = \text{Min}$ 
    else If Frame_Count > 128 AND  $\overline{E}_N > \text{Min} + 10$ 
    then  $\overline{E}_N = \text{Min}.$ 

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Figure 3 illustrates a block diagram of one possible implementation of
 a VAD 400 according to the present invention. An extractor 402 extracts the required
 predetermined parameters, including a pitch lag and a pitch gain, from the incoming

speech signal 105. A calculator unit 404 performs the necessary calculations on the extracted parameters, as illustrated by the flowcharts in Figs. 2(A) and 2(B). A decision unit 406 then determines whether a current speech frame is an active voice or a non-active voice signal and outputs a voicing decision 140 (as shown in Fig. 1).

5 Those skilled in the art will appreciate that various adaptations and modifications of the just-described preferred embodiments can be configured without departing from the scope and spirit of the invention. Therefore, it is to be understood that within the scope of the appended claims, the invention may be practiced other than as specifically described herein.

CLAIMSWhat Is Claimed Is:

- 1 1. In a speech communication system, a method for generating a frame
2 voicing decision comprising the steps of:
 - 3 (a) extracting a predetermined set of parameters, including a pitch gain
4 and a pitch lag, from the incoming speech signal for each frame;
5 and
6 (b) making a frame voicing decision according to the extracted
7 predetermined set of parameters.
- 1 2. The method according to claim 1, wherein the predetermined set of
2 parameters further comprises a full band energy and line spectral frequencies (LSF).
- 1 3. A method according to claim 2, wherein the step of making a frame
2 voicing decision further comprises the steps of:
 - 3 i. calculating a standard deviation σ of the pitch lag;
4 ii. calculating a long-term mean of pitch gain;
5 iii. calculating a short-term average of energy E , \bar{E}_s ;
6 iv. calculating a short-term average of \bar{LSFs} ;
7 v. calculating an average energy \bar{E} ; and
8 vi. calculating an average LSF value, \bar{LSF}_N .
- 1 4. A method according to claim 3, wherein the step of making a frame
2 voicing decision further comprises the steps of:
 - 3 i) calculating a spectral difference SD_1 using a normalized
4 Itakura-Saito measure;
5 ii) calculating a spectral difference SD_2 using a mean
6 square error method;
7 iii) calculating a spectral difference SD_3 using a mean
8 square error method; and
9 iv) calculating a long-term mean of SD_2 .

1 5. A method according to claim 4, wherein an initial frame voicing
2 decision is made according to the calculated values.

1 6. A method according to claim 5, wherein the initial frame voicing
2 decision is smoothed.

1 7. A method according to claim 6, wherein an initialization routine is
2 performed for a predetermined number of initial frames, such that the voicing decision
3 is set to active voice.

1 8. A voice activity detector (VAD) for making a voicing decision on an
2 incoming speech signal frame, the VAD comprising:

3 an extractor for extracting a predetermined set of parameters,
4 including a pitch gain and a pitch lag, from the incoming speech signal
5 for each frame;

6 a calculator unit for calculating a set of predetermined values
7 based on the extracted predetermined set of parameters; and

8 a decision unit for making a frame voicing decision according
9 to the predetermined set of values.

1 9. The VAD according to claim 8, wherein the predetermined set of
2 parameters further comprises a full band energy and line spectral frequencies (LSF).

1 10. The VAD according to claim 9, wherein the calculator unit calculates:

2 a standard deviation σ of the pitch lag;

3 a long-term mean of pitch gain;

4 a short-term average of energy E , \bar{E}_s ;

5 a short-term average of LSF, \overline{LSFs} ;

6 an average energy \bar{E} ; and

7 an average LSF value, $\overline{LSF_N}$.

1 11. The VAD according to claim 10, wherein the calculator unit further
2 calculates:

3 a spectral difference SD , using a normalized Itakura-Saito

4 measure;

5 a spectral difference SD_2 using a mean square error method;

6 a spectral difference SD_3 using a mean square error method;

7 and

8 a long-term mean of SD_2 .

1 12. The VAD according to claim 11, wherein the decision unit makes an
2 initial frame voicing decision according to the values calculated by the calculation
3 means

1 13. The VAD according to claim 12, wherein the initial frame voicing
2 decision is smoothed:

1 14. A voice activity detection method for detecting voice activity in an
2 incoming speech signal frame, the improvement comprising making a voicing
3 decision based on a pitch lag and a pitch gain of the speech signal frame.

1 15. The voice activity detection method of claim 14, further comprising
2 making the voicing decision based on a frame full band energy and a set of spectral
3 parameters called Line Spectral Frequencies (LSF).

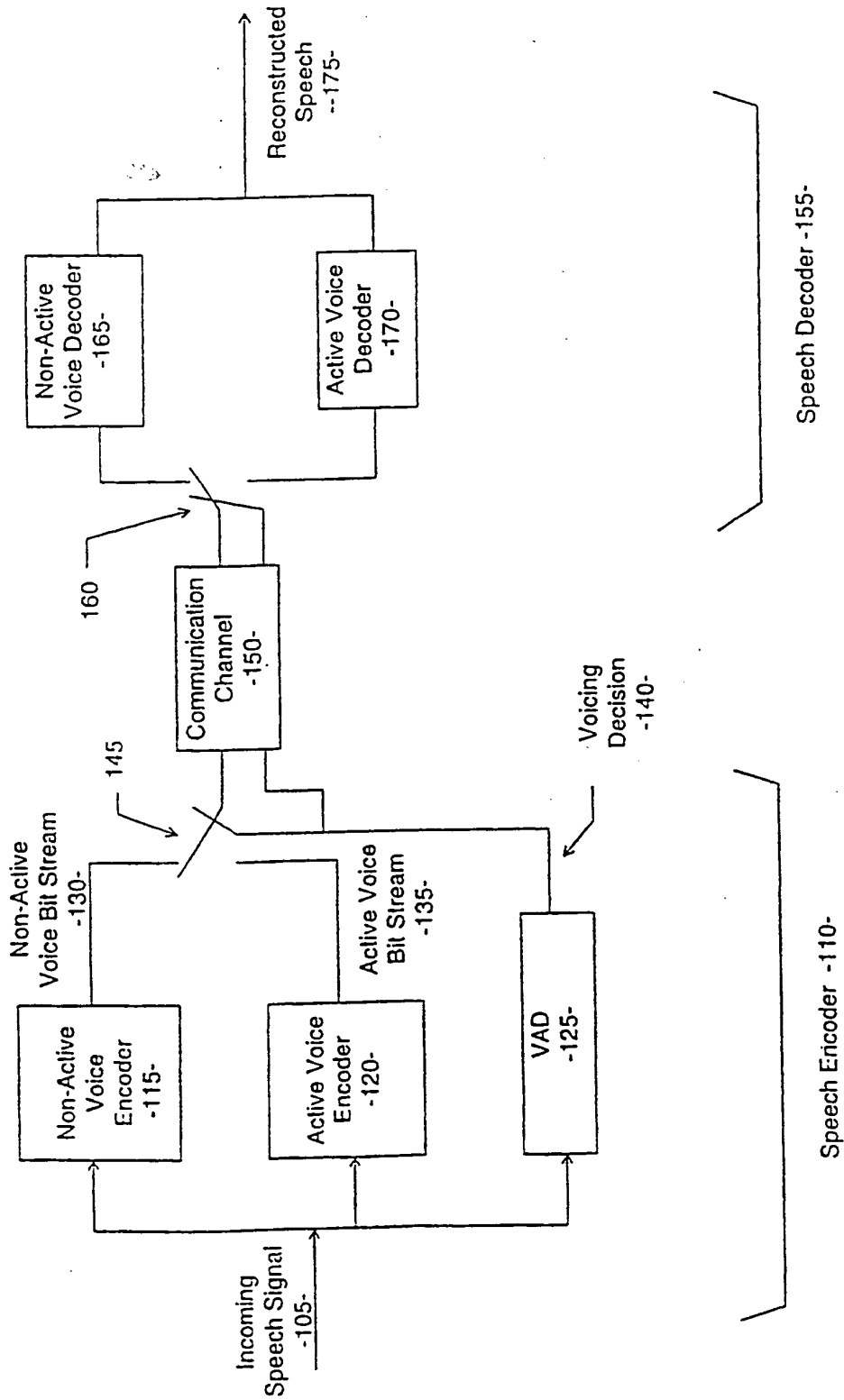
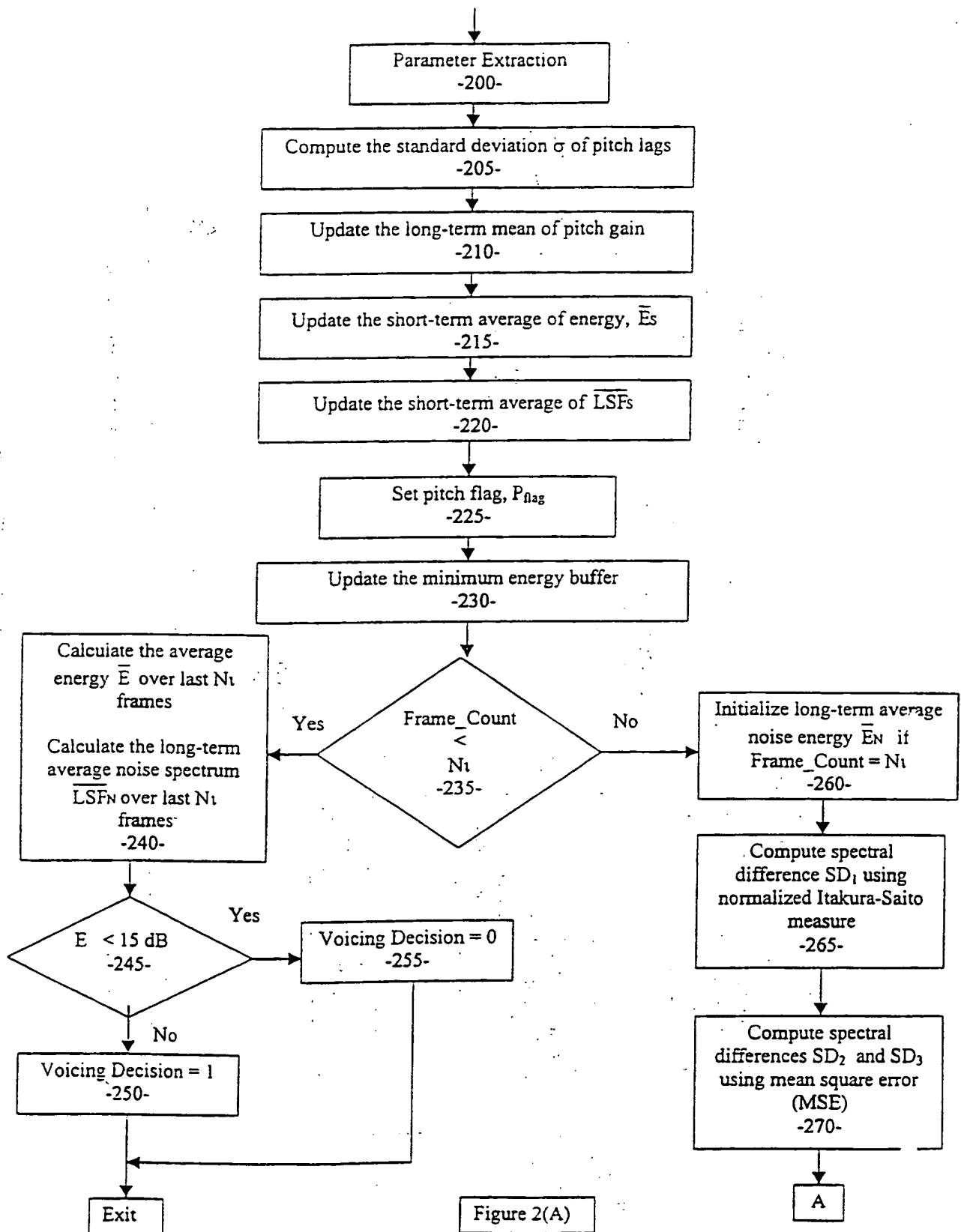


Figure 1 Prior Art

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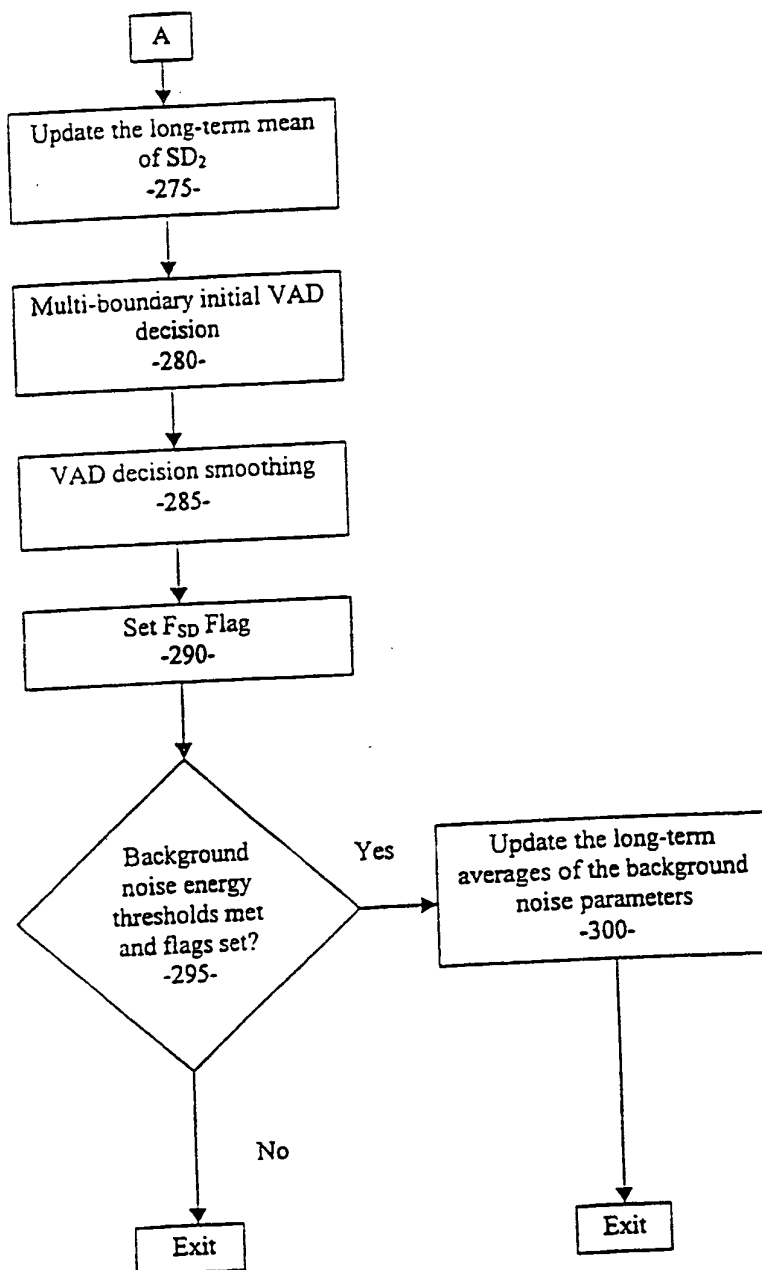


Figure 2(B)

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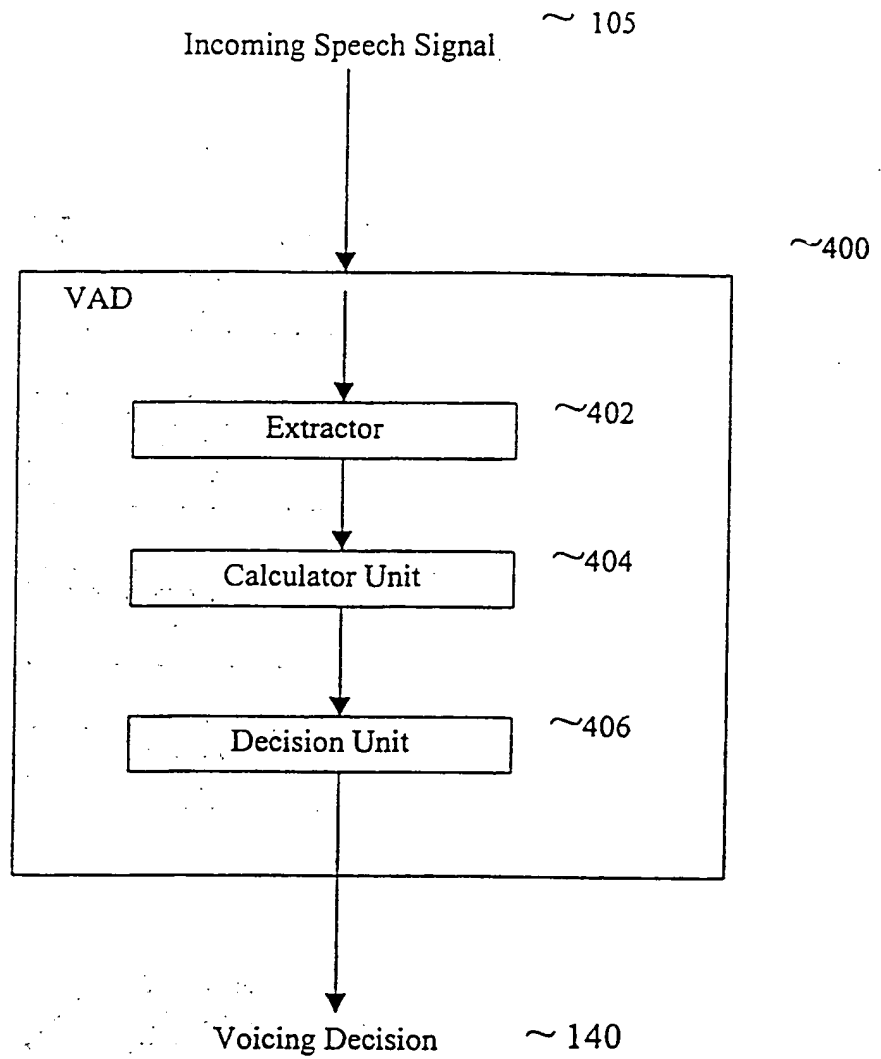


Figure 3

INTERNATIONAL SEARCH REPORT

In International Application No.

PCT/US 99/19806

A. CLASSIFICATION OF SUBJECT MATTER
IPC 7 G10L11/02

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)
IPC 7 G10L

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	EP 0 784 311 A (NOKIA MOBILE PHONES LTD) 16 July 1997 (1997-07-16) abstract; figure 2 page 8, line 15 - line 20	1, 8, 14
Y		2-4, 9-11, 15
Y	EP 0 785 419 A (ROCKWELL INTERNATIONAL CORP) 23 July 1997 (1997-07-23) cited in the application claims 1-14	2-4, 9-11, 15

☐ Further documents are listed in the continuation of box C.☒ Patent family members are listed in annex.

* Special categories of cited documents:

"A" document defining the general state of the art which is not considered to be of particular relevance

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Date of the actual completion of the international search

23 December 1999

Date of mailing of the international search report

11/01/2000

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INTERNATIONAL SEARCH REPORT

Information on patent family members

International Application No

PCT/US 99/19806

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
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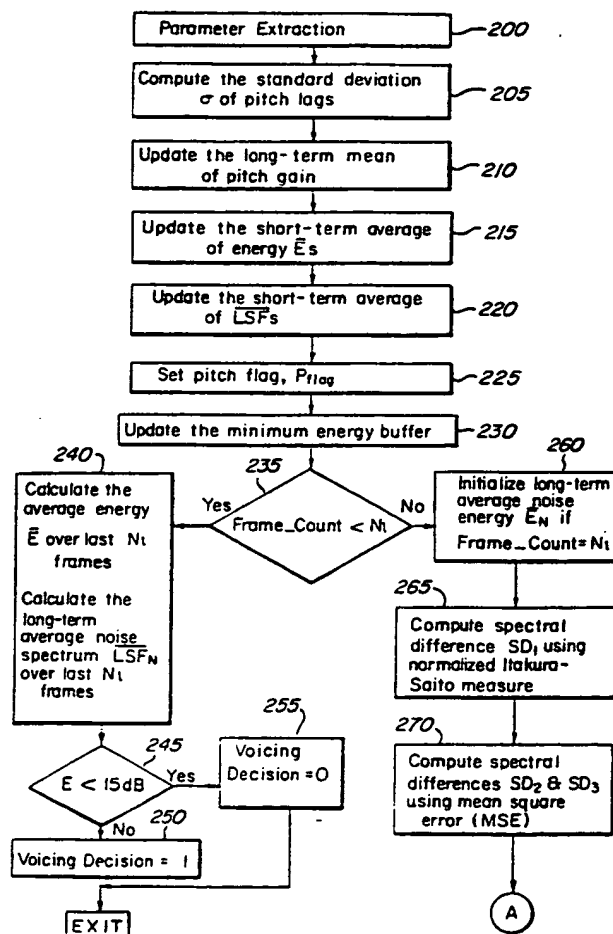
INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(51) International Patent Classification ⁷ : G10L 11/02	A1	(11) International Publication Number: WO 00/17856 (43) International Publication Date: 30 March 2000 (30.03.00)
(21) International Application Number: PCT/US99/19806 (22) International Filing Date: 27 August 1999 (27.08.99) (30) Priority Data: 09/156,416 18 September 1998 (18.09.98) US (71) Applicant: CONEXANT SYSTEMS, INC. [US/US]; Joseph King, 4311 Jamboree Road, Newport Beach, CA 92660-3095 (US). (72) Inventors: BENYASSINE, Adil; 1305 Reggio Aisle, Irvine, CA 92614 (US). SHLOMOT, Eyal; 86 Costero Aisle, Irvine, CA 92614 (US). (74) Agent: GESS, Albin, H.; Price, Gess & Ubell, 2100 S.E. Main Street, Suite 250, Irvine, CA 92614 (US).		(81) Designated States: CA, CN, JP, European patent (AT, BE, CH, CY, DE, DK, ES, FI, FR, GB, GR, IE, IT, LU, MC, NL, PT, SE). Published With international search report.

(54) Title: METHOD AND APPARATUS FOR DETECTING VOICE ACTIVITY IN A SPEECH SIGNAL

(57) Abstract

A method and apparatus for generating frame voicing decisions for an incoming speech signal having periods of active voice and non-active voice for a speech encoder in a speech communications system. A predetermined set of parameters is extracted from the incoming speech signal, including a pitch gain and a pitch lag. A frame voicing decision is made for each frame of the incoming speech signal according to values calculated from the extracted parameters. The predetermined set of parameters further includes a frame full band energy, and a set of spectral parameters called Line Spectral Frequencies (LSF).



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METHOD AND APPARATUS FOR DETECTING VOICE ACTIVITY IN A SPEECH SIGNAL

5

BACKGROUND OF THE INVENTION

1. Field of the Invention

The present invention relates generally to the field of speech coding in communication systems, and more particularly to detecting voice activity in a communications system.

10

2. Description of Related Art

Modern communication systems rely heavily on digital speech processing in general, and digital speech compression in particular, in order to provide efficient systems. Examples of such communication systems are digital telephony trunks, voice mail, voice annotation, answering machines, digital voice over data links, etc.

15

A speech communication system is typically comprised of an encoder, a communication channel and a decoder. At one end of a communications link, the speech encoder converts a speech signal which has been digitized into a bit-stream. The bit-stream is transmitted over the communication channel (which can be a storage medium), and is converted again into a digitized speech signal by the decoder at the other end of the communications link.

20

The ratio between the number of bits needed for the representation of the digitized speech signal and the number of bits in the bit-stream is the compression ratio. A compression ratio of 12 to 16 is presently achievable, while still maintaining a high quality reconstructed speech signal.

25

A significant portion of normal speech is comprised of silence, up to an average of 60% during a two-way conversation. During silence, the speech input

device, such as a microphone, picks up the environment or background noise. The noise level and characteristics can vary considerably, from a quiet room to a noisy street or a fast moving car. However, most of the noise sources carry less information than the speech signal and hence a higher compression ratio is achievable during the silence periods. In the following description, speech will be denoted as "active-voice" and silence or background noise will be denoted as "non-active-voice".

The above discussion leads to the concept of dual-mode speech coding schemes, which are usually also variable-rate coding schemes. The active-voice and the non-active voice signals are coded differently in order to improve the system efficiency, thus providing two different modes of speech coding. The different modes of the input signal (active-voice or non-active-voice) are determined by a signal classifier, which can operate external to, or within, the speech encoder. The coding scheme employed for the non-active-voice signal uses less bits and results in an overall higher average compression ratio than the coding scheme employed for the active-voice signal. The classifier output is binary, and is commonly called a "voicing decision." The classifier is also commonly referred to as a Voice Activity Detector ("VAD").

A schematic representation of a speech communication system which employs a VAD for a higher compression rate is depicted in Figure 1. The input to the speech encoder 110 is the digitized incoming speech signal 105. For each frame of a digitized incoming speech signal the VAD 125 provides the voicing decision 140, which is used as a switch 145 between the active-voice encoder 120 and the non-active-voice encoder 115. Either the active-voice bit-stream 135 or the non-active-voice bit-stream 130, together with the voicing decision 140 are transmitted through the communication channel 150. At the speech decoder 155 the voicing decision is used in the switch 160 to select the non-active-voice decoder 165 or the active-voice decoder 170. For each frame, the output of either decoders is used as the reconstructed speech 175.

An example of a method and apparatus which employs such a dual-mode system is disclosed in U.S. Patent No. 5,774,849, commonly assigned to the present

assignee and herein incorporated by reference. According to U.S. Patent No. 5,774,849, four parameters are disclosed which may be used to make the voicing decision. Specifically, the full band energy, the frame low-band energy, a set of parameters called Line Spectral Frequencies ("LSF") and the frame zero crossing rate are compared to a long-term average of the noise signal. While this algorithm provides satisfactory results for many applications, the present inventors have determined that a modified decision algorithm can provide improved performance over the prior art voicing decision algorithms.

SUMMARY OF THE INVENTION

10 A method and apparatus for generating frame voicing decisions for an incoming speech signal having periods of active voice and non-active voice for a speech encoder in a speech communications system. A predetermined set of parameters is extracted from the incoming speech signal, including a pitch gain and a pitch lag. A frame voicing decision is made for each frame of the incoming speech signal according to values calculated from the extracted parameters. The
15 predetermined set of parameters further includes a frame full band energy, and a set of spectral parameters called Line Spectral Frequencies (LSF).

BRIEF DESCRIPTION OF THE DRAWINGS

20 The exact nature of this invention, as well as its objects and advantages, will become readily apparent from consideration of the following specification as illustrated in the accompanying drawings, in which like reference numerals designate like parts throughout the figures thereof, and wherein:

Figure 1 is a block diagram representation of a speech communication
25 system using a VAD;

Figures 2(A) and 2(B) are process flowcharts illustrating the operation of the VAD in accordance with the present invention; and

Figure 3 is a block diagram illustrating one embodiment of a VAD according to the present invention.

DETAILED DESCRIPTION
OF THE PREFERRED EMBODIMENTS

The following description is provided to enable any person skilled in the art to make and use the invention and sets forth the best modes contemplated by the inventor for carrying out the invention. Various modifications, however, will remain readily apparent to those skilled in the art, since the basic principles of the present invention have been defined herein specifically to provide a voice activity detection method and apparatus.

In the following description, the present invention is described in terms of functional block diagrams and process flow charts, which are the ordinary means for those skilled in the art of speech coding for describing the operation of a VAD. The present invention is not limited to any specific programming languages, or any specific hardware or software implementation, since those skilled in the art can readily determine the most suitable way of implementing the teachings of the present invention.

In the preferred embodiment, a Voice Activity Detection (VAD) module is used to generate a voicing decision which switches between an active-voice encoder/decoder and a non-active-voice encoder/decoder. The binary voicing decision is either 1 (TRUE) for the active-voice or 0 (FALSE) for the non-active-voice.

The VAD process flowchart is illustrated in Figures 2(A) and 2(B). The VAD operates on frames of digitized speech. The frames are processed in time order and are consecutively numbered from the beginning of each conversation/recording. The illustrated process is performed once per frame.

At the first block 200, four parametric features are extracted from the input signal. Extraction of the parameters can be shared with the active-voice encoder module 120 and the non-active-voice encoder module 115 for computational efficiency. The parameters are the frame full band energy, a set of spectral parameters called Line Spectral Frequencies ("LSF"), the pitch gain and the pitch lag. A set of

linear prediction coefficients is derived from the auto correlation and a set of

$\{\overline{LSF}_i\}_{i=1}^p$ is derived from the set of linear prediction coefficients, as described in ITU-T, Study Group 15 Contribution - Q. 12/15, Draft Recommendation G.729, June 8, 1995, Version 5.0, or DIGITAL SPEECH - Coding for Low Bit Rate

- 5 Communication Systems by A.M. Kondozi, John Wiley & Son, 1994, England. The full band energy E is the logarithm of the normalized first auto correlation coefficient $R(0)$:

$$E = 10 \cdot \log_{10} \left[\frac{1}{N} R(0) \right],$$

where N is a predetermined normalization factor.

- 10 The pitch gain is a measure of the periodicity of the input signal. The higher the pitch gain, the more periodic the signal, and therefore the greater the likelihood that the signal is a speech signal. The pitch lag is the fundamental frequency of the speech (active-voice) signal.

- After the parameters are extracted, the standard deviation σ of the pitch lags of the last four previous frames are computed at block 205. The long-term mean of the pitch gain is updated with the average of the pitch gain from the last four frames at block 210. In the preferred embodiment, the long-term mean of the pitch gain is calculated according to the following formula:

$$\overline{P_{\text{gain}}} = 0.8 * \overline{P_{\text{gain}}} + 0.2 * [\text{average of last four frames}]$$

20

- The short-term average of energy, $\overline{E_s}$, is updated at block 215 by averaging the last three frames with the current frame energy. Similarly, the short-term average of LSF vectors, \overline{LSFs} , is updated at block 220 by averaging the last three LSF frame vectors with the current LSF frame vector extracted by the parameter
- 25 extractor at block 200. If the standard deviation σ is less than T_1 or the long-term mean of the pitch gain is greater than T_2 , then a flag P_{flag} is set to one, otherwise P_{flag}

equals zero at block 225.

If $\sigma < T_1$ OR $P_{\text{gain}} > T_2$, then $P_{\text{flag}} = 1$, else $P_{\text{flag}} = 0$.

In the preferred embodiment, $T_1 = 1.2$ and $T_2 = 0.7$. At block 230, a minimum energy
 5 buffer is updated with the minimum energy value over the last 128 frames. In other
 words, if the present energy level is less than the minimum energy level determined
 over the last 128 frames, then the value of the buffer is updated, otherwise the buffer
 value is unchanged.

If the frame count (i.e. current frame number) is less than a
 10 predetermined frame count N_1 at block 235, where N_1 is 32 in the preferred
 embodiment, an initialization routine is performed by blocks 240 - 255. At block 240
 the average energy \bar{E} , and the long-term average noise spectrum $\overline{LSF_N}$ are calculated
 over the last N_1 frames. The average energy \bar{E} is the average of the energy of the last
 N_1 frames. The initial value for \bar{E} , calculated at block 240, is:

15

$$\bar{E} = \frac{1}{N} \sum_{n=1}^N E$$

The long-term average noise spectrum $\overline{LSF_N}$ is the average of the LSF
 20 vectors of the last N_1 frames. At block 245, if the instantaneous energy E extracted at
 block 200 is less than 15 dB, then the voicing decision is set to zero (block 255),
 otherwise the voicing decision is set one (block 250). The processing for the frame is
 then completed and the next frame is processed, beginning with block 200.

The initialization processing of blocks 240-255 initializes the
 25 processing over the last few frames. It is not critical to the operation of the present
 invention and may be skipped. The calculations of block 240 are required, however.

for the proper operation of the invention and should be performed, even if the voicing decisions of blocks 245-255 are skipped. Also, during initialization, the voicing decision could always be set to "1" without significantly impacting the performance of the present invention.

5 If the frame count is not less than N_1 at block 235, then the first time through block 260 ($\text{Frame_Count} = N_1$), the long-term average noise energy \overline{E}_N is initialized by subtracting 12 dB from the average energy \overline{E} :

$$\overline{E}_N = \overline{E} - 12\text{dB}$$

10

Next, at block 265, a spectral difference value SD_1 is calculated using the normalized Itakura-Saito measure. The value SD_1 is a measure of the difference between two spectra (the current frame spectra represented by R and E_π , and the background noise spectrum represented by \vec{a}). The Itakura-Saito measure is a well-known algorithm in the speech processing art and is described in detail, for example, in *Discrete-Time Processing of Speech Signals*, Deller, John R., Proakis, John G. and Hansen, John H.L., 1987, pages 327-329, herein incorporated by reference. Specifically, SD_1 is defined by the following equation:

20

$$SD_1 = \frac{\vec{a}^T R \vec{a}}{E_\pi}$$

where E_π is the prediction error from linear prediction (LP) analysis of the current frame;

R is the auto-correlation matrix from the LP analysis of the current frame; and

25

\vec{a} is a linear prediction filter describing the background noise

obtained from \overline{LSFN} .

At block 270 the spectral differences SD_2 and SD_3 are calculated using a mean square error method according to the following equations:

$$SD_2 = \sum_{i=1}^p [\overline{LSFs(i)} - \overline{LSFN(i)}]^2$$

$$SD_3 = \sum_{i=1}^p [\overline{LSFs(i)} - \overline{LSF(i)}]^2$$

Where \overline{LSFs} is the short-term average of LSF;

\overline{LSFN} is the long-term average noise spectrum; and

LSF is the current LSF extracted by the parameter extraction.

The long-term mean of SD_2 (sm_SD_2) in the preferred embodiment is updated at block 275 according to the following equation:

$$sm_SD_2 = 0.4 * SD_2 + 0.6 * sm_SD_2$$

Thus, the long term mean of SD_2 is a linear combination of the past long-term mean and the current SD_2 value.

The initial voicing decision, obtained in block 280, is denoted by I_{in} .

The value of I_{vd} is determined according to the following decision statements:

If $\bar{E}_s \geq \bar{E}_N + X_1 \text{ dB}$
 OR
 $E > \bar{E}_N + X_2 \text{ dB}$
 then $IVD = 1;$

 If $\bar{E}_s - \bar{E}_N < X_3 \text{ dB}$
 AND $sm_SD_2 < T_3$
 AND
 $Frame_Count > 128$
 then $IVD = 0;$ else $IVD = 1;$

 If $E > 1/2 (E^{-1} + E^{-2}) + X_4 \text{ dB}$
 OR
 $SD_1 > 1.5$
 then $Ivd = 1.$

In the preferred embodiment, $X_1 = 1$, $X_2 = 3$, $X_3 = 2$, $X_4 = 7$, and $T_3 = 0.00012$.

- 5 The initial voicing decision is smoothed at block 285 to reflect the long term stationary nature of the speech signal. The smoothed voicing decision of the frame, the previous frame and the frame before the previous frame are denoted by S_{VD}^0 , S_{VD}^{-1} and S_{VD}^{-2} , respectively. Both S_{VD}^{-1} and S_{VD}^{-2} are initialized to 1 and $S_{VD}^0 = I_{VD}$. A Boolean parameter F_{VD}^{-1} is initialized to 1 and a counter denoted by C_e is initialized
- 10 to 0. The energy of the previous frame is denoted by E_{-1} . Thus, the smoothing stage is defined by:

if $F_{VD}^{-1} = 1$ and $I_{VD} = 0$ and $S_{VD}^{-1} = 1$ and $S_{VD}^{-2} = 1$
 $S_{VD}^0 = 1$
 $C_e = C_e + 1$
 if $C_e \leq T_4$ {
 $F_{VD}^{-1} = 1$
 }
 else {
 $F_{VD}^{-1} = 0$
 $C_e = 0$
 }
 }
 else
 $F_{VD}^{-1} = 1$

Ce is reset to 0 if $S_{VD}^{-1} = 1$ and $S_{VD}^{-2} = 1$ and $I_{VD} = 1$.

If $P_{\text{flag}} = 1$, then $S_{VD}^0 = 1$

5

If $E < 15$ dB, then $S_{VD}^0 = 0$

10 In the preferred embodiment, $T_4 = 14$. The final value of S_{VD}^0 represents the final voicing decision, with a value of "1" representing an active voice speech signal, and a value of "0" representing a non-active voice speech signal.

F_{SD} is a flag which indicates whether consecutive frames exhibit spectral stationarity (i.e., spectrum does not change dramatically from frame to frame). F_{SD} is set at block 290 according to the following where C_s is a counter initialized to 0.

```

    If Frame_Count > 128 AND SD3 < Ts
    then
        Cs = Cs + 1
    else
        Cs = 0;
    If Cs > N
        FSD = 1
    else
        FSD = 0.

```

In the preferred embodiment, $T_5 = 0.0005$ and $N = 20$.

The running averages of the background noise characteristics are
 5 updated at the last stage of the VAD algorithm. At block 295 and 300, the following conditions are tested and the updating takes place only if these conditions are met:

```

    If  $\bar{E}_s < \bar{E}_N + 3$  AND Pflag = 0
    then  $\bar{E}_N = \beta_{EN} * \bar{E}_N + (1 - \beta_{EN}) * [\max \text{ of } E \text{ AND } \bar{E}_s]$ 
    AND  $\overline{LSF}_N(i) = \beta_{LSF} * \overline{LSF}_N(i) + (1 - \beta_{LSF}) * LSF(i) \quad i = 1, \dots, p$ 
    If Frame_Count > 128 AND
         $\bar{E}_N < \text{Min}$  AND  $F_{SD} = 1$  AND Pflag = 0
    then  $\bar{E}_N = \text{Min}$ 
    else If Frame_Count > 128 AND  $\bar{E}_N > \text{Min} + 10$ 
    then  $\bar{E}_N = \text{Min}$ .

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Figure 3 illustrates a block diagram of one possible implementation of a VAD 400 according to the present invention. An extractor 402 extracts the required predetermined parameters, including a pitch lag and a pitch gain, from the incoming

speech signal 105. A calculator unit 404 performs the necessary calculations on the extracted parameters, as illustrated by the flowcharts in Figs. 2(A) and 2(B). A decision unit 406 then determines whether a current speech frame is an active voice or a non-active voice signal and outputs a voicing decision 140 (as shown in Fig. 1).

5 Those skilled in the art will appreciate that various adaptations and modifications of the just-described preferred embodiments can be configured without departing from the scope and spirit of the invention. Therefore, it is to be understood that within the scope of the appended claims, the invention may be practiced other than as specifically described herein.

CLAIMSWhat Is Claimed Is:

- 1 1. In a speech communication system, a method for generating a frame
2 voicing decision comprising the steps of:
3 (a) extracting a predetermined set of parameters, including a pitch gain
4 and a pitch lag, from the incoming speech signal for each frame;
5 and
6 (b) making a frame voicing decision according to the extracted
7 predetermined set of parameters.
- 1 2. The method according to claim 1, wherein the predetermined set of
2 parameters further comprises a full band energy and line spectral frequencies (LSF).
- 1 3. A method according to claim 2, wherein the step of making a frame
2 voicing decision further comprises the steps of:
3 i. calculating a standard deviation σ of the pitch lag;
4 ii. calculating a long-term mean of pitch gain;
5 iii. calculating a short-term average of energy E , \bar{E}_s ;
6 iv. calculating a short-term average of \overline{LSFs} ;
7 v. calculating an average energy \bar{E} ; and
8 vi. calculating an average LSF value, $\overline{LSF_N}$.
- 1 4. A method according to claim 3, wherein the step of making a frame
2 voicing decision further comprises the steps of:
3 i) calculating a spectral difference SD_1 using a normalized
4 Itakura-Saito measure;
5 ii) calculating a spectral difference SD_2 using a mean
6 square error method;
7 iii) calculating a spectral difference SD_3 using a mean
8 square error method; and
9 iv) calculating a long-term mean of SD_2 .

1 5. A method according to claim 4, wherein an initial frame voicing
2 decision is made according to the calculated values.

1 6. A method according to claim 5, wherein the initial frame voicing
2 decision is smoothed.

1 7. A method according to claim 6, wherein an initialization routine is
2 performed for a predetermined number of initial frames, such that the voicing decision
3 is set to active voice.

1 8. A voice activity detector (VAD) for making a voicing decision on an
2 incoming speech signal frame, the VAD comprising:
3 an extractor for extracting a predetermined set of parameters,
4 including a pitch gain and a pitch lag, from the incoming speech signal
5 for each frame;
6 a calculator unit for calculating a set of predetermined values
7 based on the extracted predetermined set of parameters; and
8 a decision unit for making a frame voicing decision according
9 to the predetermined set of values.

1 9. The VAD according to claim 8, wherein the predetermined set of
2 parameters further comprises a full band energy and line spectral frequencies (LSF).

1 10. The VAD according to claim 9, wherein the calculator unit calculates:
2 a standard deviation σ of the pitch lag;
3 a long-term mean of pitch gain;
4 a short-term average of energy E , \bar{E}_s ;
5 a short-term average of LSF, \overline{LSFs} ;
6 an average energy \bar{E} ; and
7 an average LSF value, $\overline{LSF_N}$.

1 11. The VAD according to claim 10, wherein the calculator unit further
2 calculates:

3 a spectral difference SD_i using a normalized Itakura-Saito

4 measure;
5 a spectral difference SD_2 using a mean square error method;
6 a spectral difference SD_2 using a mean square error method;
7 and
8 a long-term mean of SD_2 .

1 12. The VAD according to claim 11, wherein the decision unit makes an
2 initial frame voicing decision according to the values calculated by the calculation
3 means

1 13. The VAD according to claim 12, wherein the initial frame voicing
2 decision is smoothed.

1 14. A voice activity detection method for detecting voice activity in an
2 incoming speech signal frame, the improvement comprising making a voicing
3 decision based on a pitch lag and a pitch gain of the speech signal frame.

1 15. The voice activity detection method of claim 14, further comprising
2 making the voicing decision based on a frame full band energy and a set of spectral
3 parameters called Line Spectral Frequencies (LSF).

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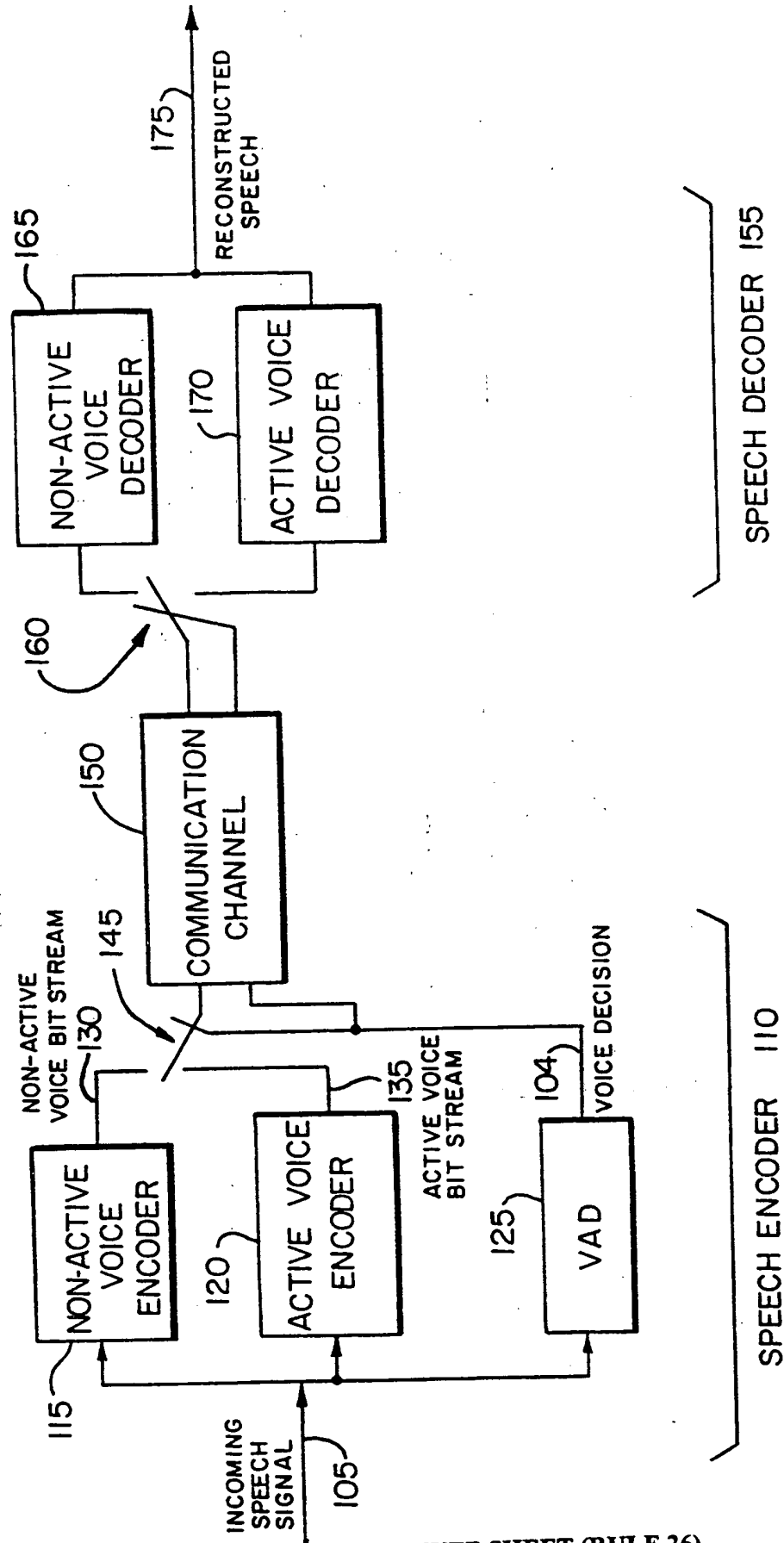


FIG. 1
PRIOR ART

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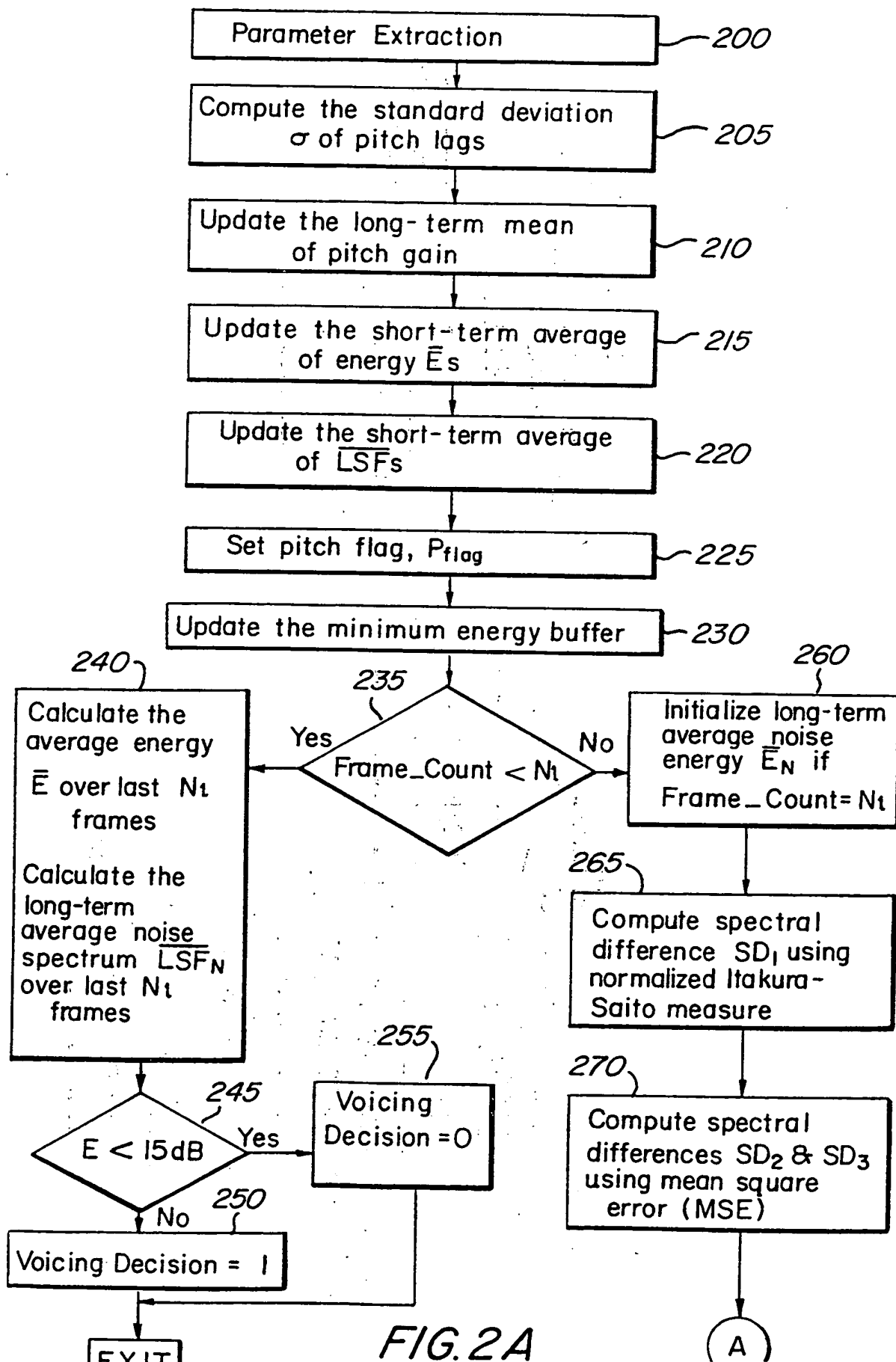


FIG. 2A

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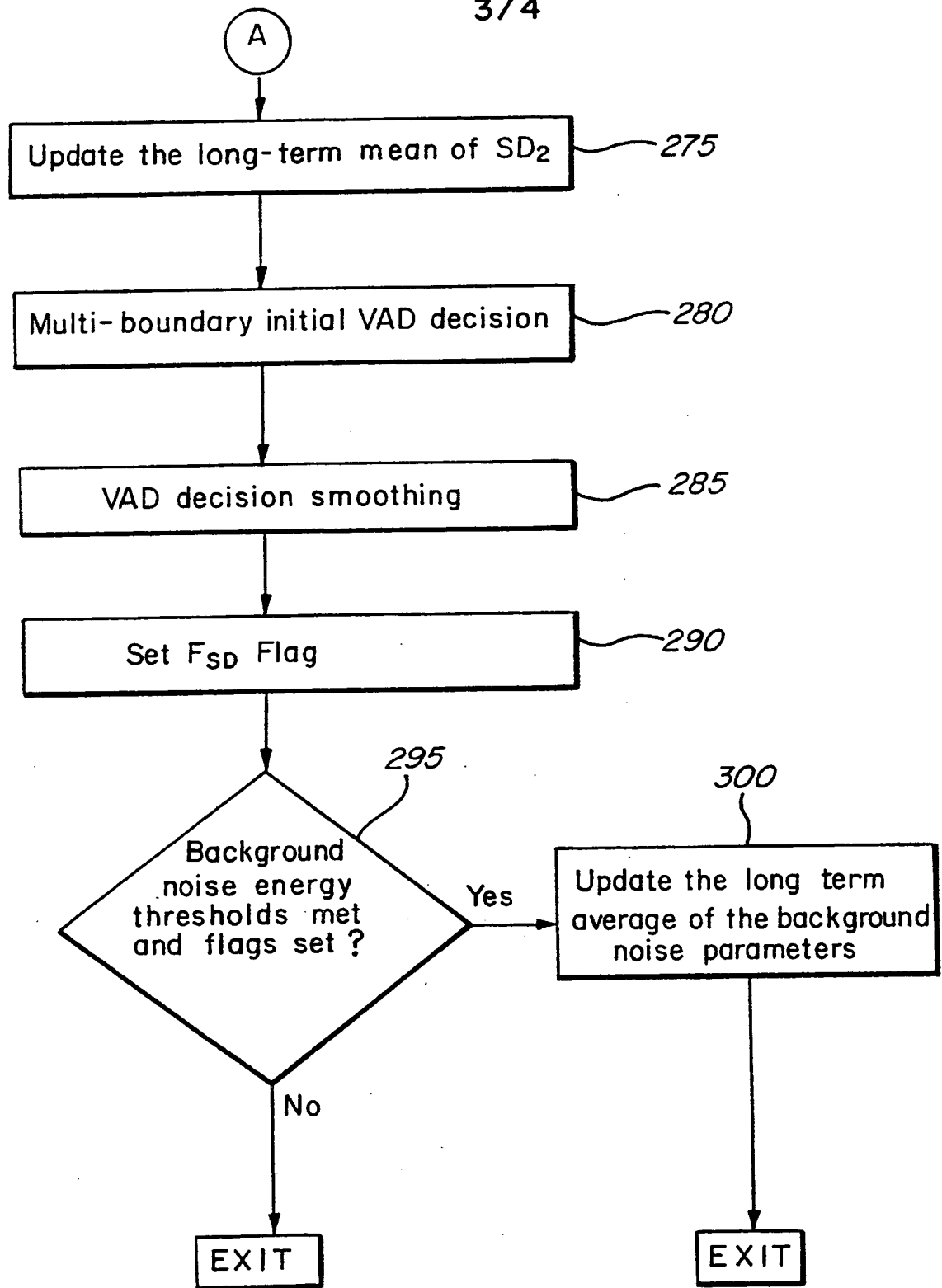
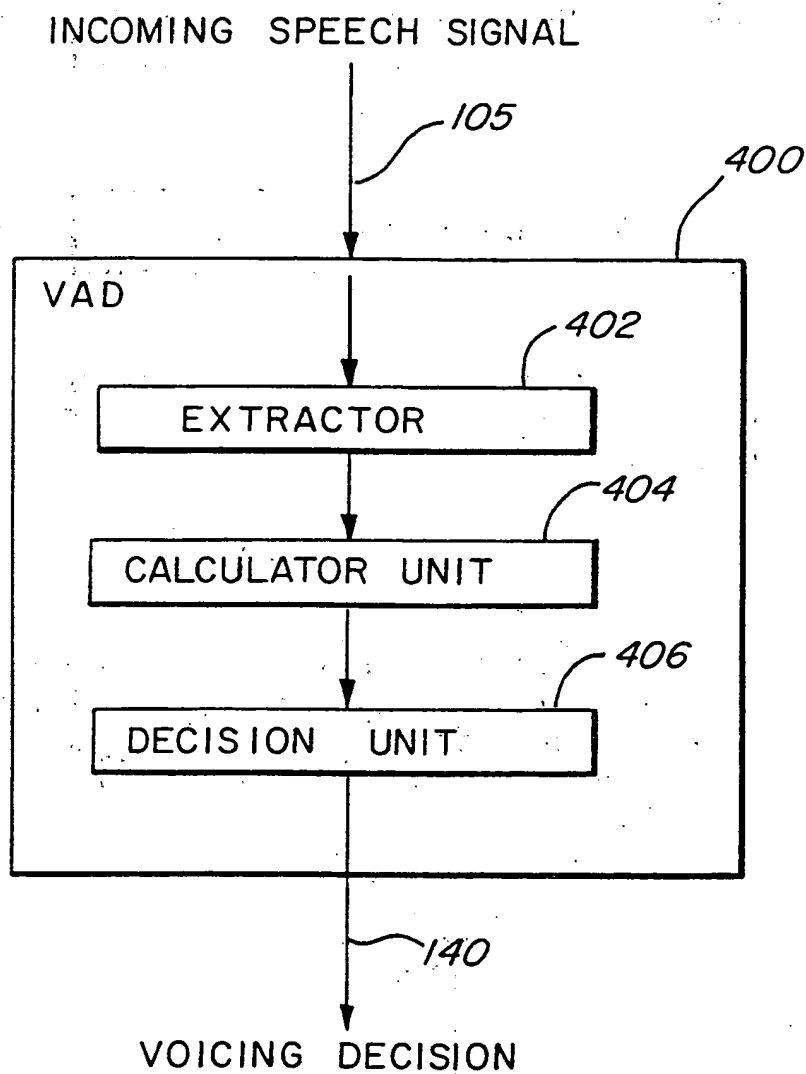


FIG. 2B

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FIG. 3



INTERNATIONAL SEARCH REPORT

In International Application No.

PCT/US 99/19806

A. CLASSIFICATION OF SUBJECT MATTER
IPC 7 G10L11/02

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHEDMinimum documentation searched (classification system followed by classification symbols)
IPC 7 G10L

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	EP 0 784 311 A (NOKIA MOBILE PHONES LTD) 16 July 1997 (1997-07-16) abstract; figure 2 page 8, line 15 - line 20	1, 8, 14
Y		2-4, 9-11, 15
Y	EP 0 785 419 A (ROCKWELL INTERNATIONAL CORP) 23 July 1997 (1997-07-23) cited in the application claims 1-14	2-4, 9-11, 15



Further documents are listed in the continuation of box C.



Patent family members are listed in annex.

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Date of the actual completion of the international search

23 December 1999

Date of mailing of the international search report

11/01/2000

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Information on patent family members

International Application No.

PCT/US 99/19806

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